



## Calhoun: The NPS Institutional Archive

---

Faculty and Researcher Publications

Faculty and Researcher Publications

---

1997-05

# On bi-decomposition of logic functions

Sasao, Tsutomu

---

International Workshop on Logic Synthesis, Lake Tahoe, California, May 18-21, 1997, vol.2,  
Session 8-1, pp.1-6.

<http://hdl.handle.net/10945/35844>



Calhoun is a project of the Dudley Knox Library at NPS, furthering the precepts and goals of open government and government transparency. All information contained herein has been approved for release by the NPS Public Affairs Officer.

**Dudley Knox Library / Naval Postgraduate School**  
**411 Dyer Road / 1 University Circle**  
**Monterey, California USA 93943**

<http://www.nps.edu/library>

# On Bi-Decompositions of Logic Functions

Tsutomu Sasao

Department of Computer Science  
and Electronics  
Kyushu Institute of Technology  
Iizuka 820, Japan

Jon T. Butler

Department of Electrical and  
Computer Engineering  
Naval Postgraduate School  
Monterey, CA 93943-5121, U.S.A.

## Abstract

A logic function  $f$  has a disjoint bi-decomposition iff  $f$  can be represented as  $f = h(g_1(X_1), g_2(X_2))$ , where  $X_1$  and  $X_2$  are disjoint set of variables, and  $h$  is an arbitrary two-variable logic function.  $f$  has a non-disjoint bi-decomposition iff  $f$  can be represented as  $f(X_1, X_2, x) = h(g_1(X_1, x), g_2(X_2, x))$ , where  $x$  is the common variable. In this paper, we show a fast method to find bi-decompositions. Also, we enumerate the number of functions having bi-decompositions.

## I Introduction

Functional decomposition is a basic technique to realize economical networks. If the function  $f$  is represented as  $f(X_1, X_2) = h(g(X_1), X_2)$ , then  $f$  can be realized by the network shown in Fig. 1.1. To find such a decomposition,

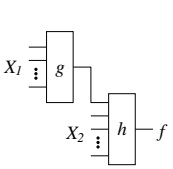


Figure 1.1: A simple disjoint bi-decomposition.

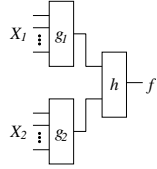


Figure 1.2: A disjoint bi-decomposition.

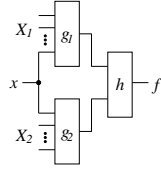


Figure 1.3: A non-disjoint bi-decomposition.

a decomposition chart with  $2^{n_1}$  columns and  $2^{n_2}$  rows are used, where  $n_i$  is the number of variables in  $X_i$  ( $i = 1, 2$ ). When  $n$  is large, the decomposition chart is too large to build. Recently, a method using BDDs has been developed [13]. This greatly reduces memory requirements and computation time. However, it is still time consuming, since we have to check all the  $\binom{n_1+n_2}{n_1}$  partitions of  $n = n_1 + n_2$ . In this paper, we consider bi-decompositions of logic functions, a restricted class of functional decompositions that have the form  $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$ . Fig. 1.2 shows the realization of this decomposition.

The reasons we consider bi-decompositions are as follows:

- 1) If  $f$  has no bi-decomposition, then the computation time is quite small.

- 2) Some programmable logic devices have two-input logic elements in the outputs.
- 3) If  $f$  has a bi-decomposition, then the optimization of the expression is relatively easy.

A restricted class of bi-decompositions has been considered by [8]. The goals of this paper are

- 1) Present a fast method for finding bi-decompositions.
- 2) Enumerate the functions that have bi-decompositions.

Most of the proofs are omitted. They can be available from authors.

## II Disjoint Bi-Decomposition

**Definition 2.1** Let  $X = (X_1, X_2)$  be a partition of the variables. A logic function  $f$  has a disjoint bi-decomposition iff  $f$  can be represented as  $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$ , where  $h$  is any two-variable logic function.

If  $f$  has a disjoint bi-decomposition, then  $f$  can be realized by the network shown in Fig. 1.2.

**Definition 2.2** Let  $X = (X_1, X_2)$  be a partition of the variables. Let  $n_1$  and  $n_2$  be the number of variables in  $X_1$  and  $X_2$ , respectively. A decomposition chart of the function  $f$  for a partition  $(X_1, X_2)$  consists of  $2^{n_1}$  columns and  $2^{n_2}$  rows of 0s and 1s. The  $2^{n_1}$  distinct binary numbers for  $X_1$  are listed across the top, and the  $2^{n_2}$  distinct binary numbers for  $X_2$  are listed down the side. The entry for the chart corresponds to the value of  $f(X_1, X_2)$ .

**Example 2.1** Two decomposition charts for the function  $f(x_1, x_2, x_3, x_4) = x_1x_2 \oplus x_3x_4$  are shown in Fig. 2.1 (a) and (b).  $\square$

Note that the decomposition chart is similar to the Karnaugh map with a different ordering for the cell locations.

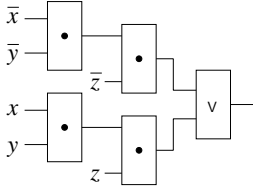
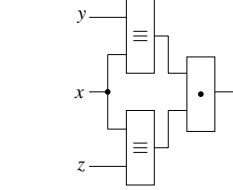
**Definition 2.3** The number of distinct column (row) patterns in the decomposition chart is called column (row) multiplicity.

		$X_1 = (x_1, x_2)$						$X_1 = (x_1, x_3)$					
		00	01	10	11			00	01	10	11		
$X_2 = (x_3, x_4)$	00	0	0	0	1			00	0	0	0	0	
	01	0	0	0	1			01	0	1	0	1	
	10	0	0	0	1			10	0	0	1	1	
	11	1	1	1	0			11	0	1	1	0	

(a)

(b)

Figure 2.1: Decomposition chart.

Figure 3.1: A realization of  $f(x, y, z) = \bar{x}\bar{y}\bar{z} \vee xyz$ .Figure 3.2: Non-disjoint bi-decomposition for  $f(x, y, z) = \bar{x}\bar{y}\bar{z} \vee xyz$ .

**Example 2.2** In Fig. 2.1 (a), the row and column multiplicities are two. In Fig. 2.1 (b), the row and column multiplicities are four.  $\square$

**Definition 2.4** Let  $\mu(f : X_1, X_2)$  be the column multiplicities for  $f$  with respect to  $X_1$  and  $X_2$ . Let  $\mu(f : X_2, X_1)$  be the row multiplicities for  $f$  with respect to  $X_1$  and  $X_2$ .

**Theorem 2.1**  $f$  has a disjoint bi-decomposition of form  $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$  iff  $\mu(f : X_1, X_2) \leq 2$  and  $\mu(f : X_2, X_1) \leq 2$ .

### III Non-Disjoint Bi-Decomposition

**Definition 3.1** Let  $X_1$  and  $X_2$  be disjoint sets of variables, and let  $x$  be disjoint from  $X_1$  and  $X_2$ . A logic function  $f$  has a non-disjoint bi-decomposition iff  $f$  can be represented as  $f(X_1, X_2, x) = h(g_1(X_1, x), g_2(X_2, x))$ , where  $h$  is a two-variable logic function. In this case,  $x$  is called the common variable.

A function  $f$  with a non-disjoint bi-decomposition can be realized by the network shown in Fig. 1.3.

**Lemma 3.1** Let  $X = (X_1, X_2, x)$  be a partition of the input variables. Let  $h(g_1, g_2)$  be an arbitrary logic function of two variables. Then,

$$h(g_1(X_1, x), g_2(X_2, x)) = \bar{x}h(g_1(X_1, 0), g_2(X_2, 0)) \vee xh(g_1(X_1, 1), g_2(X_2, 1)).$$

**Definition 3.2** Let  $x$  be the common variable of the non-disjoint bi-decomposition. Let  $f(X_1, X_2, a)$  be a sub-function, where  $x$  is set to a 0 or 1.

		$X_1 = (x_1, x_2)$						$X_1 = (x_1, x_2)$					
		00	01	10	11			00	01	10	11		
$X_2 = (x_3, x_4)$	00	1	0	0	0			00	0	0	0	1	
	01	1	0	0	0			01	1	1	1	0	
	10	1	0	0	0			10	1	1	1	0	
	11	0	1	1	1			11	1	1	1	0	

(a)  $f_0 = \bar{x}_1 \bar{x}_2 \oplus x_3 x_4$ (b)  $f_1 = x_1 x_2 \oplus (x_3 \vee x_4)$ 

Figure 3.3: Functions in Example 3.2

**Theorem 3.1**  $f(X_1, X_2, x)$  has a non-disjoint bi-decomposition of the form  $h(g_1(X_1, x), g_2(X_2, x))$  iff  $f(X_1, X_2, 0)$  and  $f(X_1, X_2, 1)$  have disjoint bi-decompositions  $h(g_{01}(X_1), g_{02}(X_2))$  and  $h(g_{11}(X_1), g_{12}(X_2))$ , respectively.

**Example 3.1** Consider the three-variable function:  $f(x, y, z) = \bar{x}\bar{y}\bar{z} \vee xyz$ . Suppose modules that realizes any function of two variables can be used. The straightforward realization shown in Fig. 3.1 requires five modules. The Shannon expansion with respect to  $x$  is  $f(x, y, z) = \bar{x}f(0, y, z) \vee xf(1, y, z)$ , where  $f(0, y, z) = \bar{y}\bar{z}$ , and  $f(1, y, z) = yz$ . Note that both  $f(0, y, z)$  and  $f(1, y, z)$  have bi-decompositions with  $h(x, y) = xy$ . Since,  $g_1(x, y) = \bar{x}g_{01}(X_1) \vee xg_{11}(X_1) = \bar{x}\bar{y} \vee xy$ , and  $g_2(x, y) = \bar{x}g_{02}(X_2) \vee xg_{12}(X_2) = \bar{x}\bar{z} \vee xz$ . We have  $f(x, y, z) = g_1(x, y)g_2(x, z) = (\bar{x}\bar{y} \vee xy)(\bar{x}\bar{z} \vee xz)$ . From this expression, we have the network in Fig. 3.2. This network requires only three modules.  $\square$

**Example 3.2** Consider the five-variable function  $f = \bar{x}_5 f_0 \vee x_5 f_1$ , where  $f_0$  and  $f_1$  are shown in Fig. 3.3. Since both  $f_0$  and  $f_1$  have disjoint bi-decompositions of the form  $h(g_1(X_1), g_2(X_2))$ ,  $f = \bar{x}_5 f_0 \vee x_5 f_1$  has a non-disjoint bi-decomposition as follows:

$$f = \bar{x}_5 \{ \bar{x}_1 \bar{x}_2 \oplus x_3 x_4 \} \vee x_5 \{ x_1 x_2 \oplus (x_3 \vee x_4) \} \\ = \{ \bar{x}_5 (\bar{x}_1 \bar{x}_2) \vee x_5 (x_1 x_2) \} \oplus \{ \bar{x}_5 (x_3 x_4) \vee x_5 (x_3 \vee x_4) \}.$$

The converse is true also.  $\square$

Up to now, we only considered the case where there is a single common variable. However, the theorem can be extended to  $k$  common variables, where  $k \geq 2$ .

**Definition 3.3** Let  $X_1$ ,  $X_2$ , and  $X_3$  be disjoint sets of variables. Let  $f(X_1, X_2, \mathbf{a})$  be the sub-functions, where  $X_3$  is set to  $\mathbf{a} \in \{0, 1\}^k$ , and  $k$  denotes the number of variables in  $X_3$ .

**Theorem 3.2** Let  $X_1$ ,  $X_2$ , and  $X_3$  be disjoint sets of variables. Then,  $f$  has a non-disjoint bi-decomposition of form  $f(X_1, X_2, X_3) = h(g_1(X_1, X_3), g_2(X_2, X_3))$  iff  $f(X_1, X_2, \mathbf{a})$  has a decomposition of the form  $h(g_1 \mathbf{a}(X_1), g_2 \mathbf{a}(X_2))$  for all possible  $\mathbf{a} \in \{0, 1\}^k$ , where  $k$  denotes the number of variables in  $X_3$ .

## IV A Fast Method for Bi-Decompositions

In this section, we show necessary and sufficient conditions for a function to have a disjoint bi-decomposition. Then, we show efficient algorithms to find disjoint bi-decompositions. In the previous sections,  $h(g_1, g_2)$  is an arbitrary two-variable logic function. To find a disjoint bi-decomposition, we need to consider only three types:

- 1) OR type:  $f = g_1(X_1) \vee g_2(X_2)$ ,
- 2) AND type:  $f = g_1(X_1)g_2(X_2)$ , and
- 3) EXOR type:  $f = g_1(X_1) \oplus g_2(X_2)$ .

Since  $f$  has an AND type disjoint bi-decomposition iff  $\bar{f}$  has OR type disjoint bi-decomposition, we only consider the OR type and EXOR type bi-decompositions.

**Definition 4.1**  $x$  and  $\bar{x}$  are literals of a variable  $x$ . A logical product which contains at most one literal for each variable is called a product term or a product. Product terms combined with OR operators form a sum-of-products expression (SOP).

**Definition 4.2** A prime implicant (PI)  $p$  of a function  $f$  is a product term which implies  $f$ , such that the deletion of any literal from  $p$  results in a new product which does not imply  $f$ .

**Definition 4.3** An irredundant sum-of-products expression (ISOP) is an SOP, where each product is a PI, and no product can be deleted without changing the function represented by the expression.

**Definition 4.4** Let  $f(X)$  be a function and  $p$  be a product of literal(s) in  $X$ . The restriction of  $f$  to  $p$ , denoted by  $f(X|p)$  is obtained as follows: If  $x_i$  appears in  $p$ , then set  $x_i$  in 1 in  $f$ , and if  $\bar{x}_i$  appears in  $p$ , then set  $x_i$  in 0 in  $f$ .

**Example 4.1** Let  $f(x_1, x_2, x_3) = x_1x_2 \vee \bar{x}_2x_3$  and  $p = x_1x_3$ .  $f(X|p)$  is obtained as follows: Set  $x_1 = x_3 = 1$  in  $f$ , and we have  $f(X|x_1x_3) = f(1, x_2, 1) = x_2 \vee \bar{x}_2 = 1$ .  $\square$

**Lemma 4.1**  $p$  is an implicant of  $f(X)$ , iff  $f(X|p) = 1$ .

**Example 4.2** By Lemma 4.1,  $x_1x_3$  is an implicant of  $x_1x_2 \vee \bar{x}_2x_3$ , shown in Example 4.1.  $\square$

**Theorem 4.1** (OR type disjoint bi-decomposition)  $f$  has a disjoint bi-decomposition of form  $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$  iff every product in an ISOP for  $f$  consists of literals from  $X_1$  only or  $X_2$  only.

**Definition 4.5**  $x^0 = \bar{x}$ .  $x^1 = x$ .

**Corollary 4.1** If  $f(x_1, x_2, \dots, x_n)$  has a PI of the form  $x_1^{a_1}x_2^{a_2}\dots x_n^{a_n}$ , where  $a_i \in \{0, 1\}$ , then  $f$  has no OR type disjoint bi-decomposition.

Let  $x_i (i = 1, 2, \dots, n)$  be the input variables of  $f$ . Let  $p_1 \vee p_2 \vee \dots \vee p_t$  be an irredundant sum-of-products expression for  $f$ , where  $p_i (i = 1, 2, \dots, t)$  are PIs of  $f$ . Let  $\Pi_0$  be the trivial partition of  $\{1, 2, \dots, n\}$ ,  $\Pi_0 = [\{1\}, \{2\}, \dots, \{n\}]$ .

**Algorithm 4.1** (OR type disjoint bi-decomposition:  $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$ ).

1. For  $i = 1$  to  $t$ , form  $\Pi_i$  from  $\Pi_{i-1}$  by merging two blocks  $\Omega_1$  and  $\Omega_2$  of  $\Pi_{i-1}$  if at least one literal in  $p_i$  occurs in both  $\Omega_1$  and  $\Omega_2$ .
2. If  $\Pi_t$  has at least two blocks, then  $f(X_1, X_2)$  has a disjoint bi-decomposition of the form  $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$ , with  $X_1$  the union of one or more blocks of  $\Pi_t$  and  $X_2$  the union of the remaining blocks.

**Example 4.3** Consider the ISOP:  $f(x_1, x_2, \dots, x_6) = x_1x_2 \vee x_2x_3 \vee x_4x_5 \vee x_5x_6$ . The products  $x_1x_2$  and  $x_2x_3$  show that  $x_1, x_2$ , and  $x_3$  are in the same block. Also, the products  $x_4x_5$  and  $x_5x_6$  show that  $x_4, x_5$ , and  $x_6$  are in the same block. Thus, we have the partition  $[\{1, 2, 3\}, \{4, 5, 6\}]$ . The corresponding OR type disjoint bi-decomposition is  $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$ , where  $X_1 = (x_1, x_2, x_3)$  and  $X_2 = (x_4, x_5, x_6)$ .  $\square$

**Example 4.4** Consider the function  $f$  with an ISOP:  $f(x_1, x_2, x_3, x_4, x_5) = x_1x_2x_3 \vee x_3x_4x_5$ .

- 1) The product  $x_1x_2x_3$  shows that  $x_1, x_2$ , and  $x_3$  belong to the same block.
- 2) The product  $x_3x_4x_5$  shows that  $x_3, x_4$ , and  $x_5$  belong to the same block.

Thus, all the variables belong to the same block. From this, it follows that  $f$  has no OR type decomposition.  $\square$

**Theorem 4.2** (AND type disjoint bi-decomposition)  $f$  has a disjoint bi-decomposition of form  $f(X_1, X_2) = g_1(X_1)g_2(X_2)$  iff every product in an ISOP for  $f$  consists of literals from  $X_1$  only or  $X_2$  only.

**Lemma 4.2** [15] An arbitrary  $n$ -variable function can be uniquely represented as

$$\begin{aligned} f(x_1, x_2, \dots, x_n) = & a_0 \oplus (a_1x_1 \oplus a_2x_2 \oplus \dots \oplus a_nx_n) \\ & \oplus (a_{12}x_1x_2 \oplus a_{13}x_1x_3 \oplus \dots \oplus a_{n-1n}x_{n-1}x_n) \\ & \oplus \dots \oplus a_{12\dots n}x_1x_2\dots x_n, \end{aligned} \quad (4.1)$$

where  $a_i \in \{0, 1\}$ . The above expression is called a positive polarity Reed-Muller expression (PPRM).

For a given function  $f$ , the coefficients  $a_0, a_1, a_2, \dots, a_{12\dots n}$  are uniquely determined. Thus, the PPRM is a canonical representation. The number of products in (4.1) is at most  $2^n$ , and all the literals are positive (uncomplemented).

**Theorem 4.3** (*EXOR type disjoint bi-decomposition*)  $f$  has a disjoint bi-decomposition of the form  $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$  iff every product in the PPRM for  $f$  consists of literals from  $X_1$  only or  $X_2$  only.

**Corollary 4.2** If the PPRM of an  $n$ -variable function has the product  $x_1 x_2 \cdots x_n$ , then  $f$  has no EXOR type disjoint bi-decomposition.

**Theorem 4.4** When  $f$  has an EXOR type disjoint bi-decomposition, the number of true minterms of  $f$  is an even number.

**Corollary 4.3** When the number of true minterms of  $f$  is an odd number, then  $f$  does not have an EXOR type disjoint bi-decomposition.

The significance of this observation is that at least one half of the functions can be quickly rejected as candidates for EXOR type disjoint bi-decomposition.

Let  $x_i$  ( $i = 1, 2, \dots, n$ ) be the input variables of  $f$ . Let  $p_1 \oplus p_2 \oplus \cdots \oplus p_t$  be PPRM for  $f$ , where  $p_i$  ( $i = 1, 2, \dots, t$ ) are products. Let,  $\Pi_0$  be the trivial partition of  $\{1, 2, \dots, n\}$ ,  $\Pi_0 = [\{1\}, \{2\}, \dots, \{n\}]$ .

**Algorithm 4.2** (*EXOR type disjoint bi-decomposition*):  $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$ .

1. For  $i = 1$  to  $t$ , form  $\Pi_i$  from  $\Pi_{i-1}$  by merging two blocks  $\Omega_1$  and  $\Omega_2$  of  $\Pi_{i-1}$  if at least one literal in  $p_i$  occurs in both  $\Omega_1$  and  $\Omega_2$ .
2. If  $\Pi_i$  has at least two blocks, then  $f(X_1, X_2)$  has a disjoint bi-decomposition of form  $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$ , with  $X_1$  the union of one or more blocks of  $\Pi_i$  and  $X_2$  the union of the remaining blocks.

**Example 4.5** Consider the PPRM:  $f(x_1, x_2, \dots, x_6) = x_1 x_2 \oplus x_2 x_3 \oplus x_4 x_5 \oplus x_5 x_6$ . The products  $x_1 x_2$  and  $x_2 x_3$  show that  $x_1, x_2$ , and  $x_3$  are in the same block. Also, the products  $x_4 x_5$  and  $x_5 x_6$  show that  $x_4, x_5$ , and  $x_6$  are in the same block. Thus, we have the partition  $[\{1, 2, 3\}, \{4, 5, 6\}]$ . The corresponding EXOR type disjoint bi-decomposition is  $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$ , where  $X_1 = (x_1, x_2, x_3)$  and  $X_2 = (x_4, x_5, x_6)$ .  $\square$

**Algorithm 4.3** (*Non-disjoint bi-decomposition*).  $f(X_1, X_2, x_i) = g_1(X_1, x_i) \otimes g_2(X_2, x_i)$ , where  $\otimes$  denotes either OR, AND, or EXOR. Let  $(X_1, X_2, x_i)$  be a partition of the variables  $x_1, x_2, \dots$ , and  $x_n$ . For  $i = 1$  to  $n$ , do

- i) Let  $f_{0i} = f(X_1, X_2, 0)$ . (Set  $x_i$  to 0). Let  $f_{1i} = f(X_1, X_2, 1)$ . (Set  $x_i$  to 1).
- ii) If both  $f_{0i}$  and  $f_{1i}$  have the same type of disjoint bi-decompositions with the same partition, then  $f$  has a non-disjoint bi-decomposition.

## V Complexity Analysis of the Algorithms

### 5.1 OR type disjoint bi-decomposition

We assume that the function is given as an ISOP with  $t$  products. Note that  $t \leq 2^{n-1}$ . The time to form the partition of variables is  $O(n \cdot t)$ .

### 5.2 EXOR type disjoint bi-decomposition

A PPRM can be represented by a functional decision diagram (FDD [5, 15]). Each path from the root node to the constant 1 node corresponds to a product in the PPRM. Thus, the partition of the input variables is directly generated from the FDD. The number of paths in an FDD is  $O(2^n)$ , where  $n$  is the number of the input variables. However, we can avoid exhaustive generation of paths as follows: Let  $p_1$  and  $p_2$  be products in a PPRM. If all the literals in  $p_1$  also appear in  $p_2$ , then  $p_2$  need not be generated in the Algorithm, since the product  $p_1$  that contains more literals than  $p_2$  is more important. By searching the paths with more literals first, we can efficiently detect functions with no disjoint bi-decomposition.

**Example 5.1** Consider the function  $f(X)$  given as a PPRM:  $f(X) = x_1 \oplus x_1 x_2 \oplus x_3 x_4 \oplus x_1 x_2 x_5 x_6$ . In constructing the partition of  $X$ , we need not consider the products  $x_1$  or  $x_1 x_2$ , since  $x_1 x_2 x_5 x_6$  has the literals of  $x_1$  and  $x_1 x_2$ . In this case, the product  $x_1 x_2 x_5 x_6$  shows that  $x_1, x_2, x_5$ , and  $x_6$  belong to the same group. Also, the product  $x_3 x_4$  shows that  $x_3$  and  $x_4$  belong to the same group. Thus,  $X$  is partitioned as  $X = (X_1, X_2)$ , where  $X_1 = (x_1, x_2, x_5, x_6)$  and  $X_2 = (x_3, x_4)$ .  $\square$

**Definition 5.1** Let  $p$  be a product. The set of variables in  $p$  is denoted by  $V(p) = \{x_i | x_i \text{ or } \bar{x}_i \text{ appears in } p\}$ . For example,  $V(x_1 x_2 \bar{x}_4) = \{x_1, x_2, x_4\}$

**Definition 5.2** Let  $F$  be a PPRM. A product  $p$  is said to have maximal variable set  $V(p)$  if there is no other product  $p'$  such that  $V(p) \subset V(p')$ .

**Example 5.2** For the PPRM,  $F = x_1 x_2 \oplus x_1 x_3 \oplus x_1 x_2 x_3 \oplus x_4$ ,  $V(x_1 x_2) = \{x_1, x_2\}$ ,  $V(x_1 x_3) = \{x_1, x_3\}$ ,  $V(x_1 x_2 x_3) = \{x_1, x_2, x_3\}$ , and  $V(x_4) = \{x_4\}$ . Thus,  $x_1 x_2 x_3$  and  $x_4$  have maximal variable sets.  $\square$

**Theorem 5.1** A function  $f$  has an EXOR type disjoint bi-decomposition if a function  $f'$  from the PPRM of  $f$  by eliminating implicants not having maximal variable sets has an EXOR type disjoint bi-decomposition.

The following theorem says that if a function has an EXOR type disjoint bi-decomposition, then the number of products in the PPRM is relatively small.

**Theorem 5.2** If  $f$  has a disjoint bi-decomposition of the form  $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$ , then the number of products in the PPRM is at most  $2^{n_1} + 2^{n_2} - 1$ , where  $n_i$  is the number of variables in  $X_i$  ( $i = 1, 2$ ).

## VI Number of Functions with Bi-Decompositions

### 6.1 Functions with a small number of variables

In the previous sections, we showed that disjoint bi-decompositions are easy to find. In this section, we will enumerate the functions with disjoint bi-decompositions.

**Definition 6.1** A function  $f$  is said to be nondegenerate if for all  $x_i$   $f(|\bar{x}_i) \neq f(|x_i)$ .

**Definition 6.2** Two functions  $f$  and  $g$  are NP-equivalent, denoted by  $f \stackrel{\text{NP}}{\sim} g$ , iff  $g$  is derived from  $f$  by the following operations:

- 1) Permutation of the input variables.
- 2) Negations of the input variables.

The following is easy to prove.

**Lemma 6.1** If  $f$  has a disjoint bi-decomposition and if  $f \stackrel{\text{NP}}{\sim} g$ , then  $g$  has also the same type of disjoint bi-decomposition.

**Lemma 6.2** All the two-variable functions have disjoint bi-decompositions.

**Example 6.1** There are  $2^{2^3} = 256$  three-variable logic functions of which 218 are nondegenerate. These non-degenerate functions are grouped into 16 NP-equivalence classes as shown in Table 6.1 [9]. In this table, the column headed by  $N$  denotes the number of functions in that equivalence class. Eight classes have disjoint bi-decompositions, and three have non-disjoint bi-decompositions. Note that 194 functions have bi-decompositions.  $\square$

The number of functions with AND type disjoint bi-decompositions is equal to the number of functions with OR type disjoint bi-decompositions.

In the case of disjoint bi-decompositions, a function has exactly one type of decomposition (Lemma 6.4). On the other hand, in the case of non-disjoint bi-decompositions, a function may have more than one type of bi-decompositions.

**Example 6.2** Consider the three-variable function  $f = \bar{x}_1 x_3 \vee x_1 x_2$ . This function has three types of non-disjoint bi-decompositions:

$$\begin{aligned} f &= \bar{x}_1 x_3 \vee x_1 x_2 && (\text{OR type bi-decomposition}) \\ &= \bar{x}_1 x_3 \oplus x_1 x_2 && (\text{EXOR type bi-decomposition}) \\ &= (x_1 \vee x_3)(\bar{x}_1 \vee x_2) && (\text{AND type bi-decomposition}) \end{aligned} \quad \square$$

Table 6.1: NP-representative functions of three variables.

	Representative functions	$N$	Type	Property
1	$x_1 \oplus x_2 \oplus x_3$	2	EXOR	Disjoint Bi-Decomposition
2	$x_1 x_2 x_3$	8	AND	
3	$x_1 \vee x_2 \vee x_3$	8	OR	
4	$x_1(x_2 \vee x_3)$	24	AND	
5	$x_1 \vee x_2 x_3$	24	OR	
6	$x_1(x_2 \oplus x_3)$	12	AND	
7	$x_1 \vee (x_2 \oplus x_3)$	12	OR	
8	$x_1 \oplus x_2 x_3$	24	EXOR	
9	$x_1 x_2 x_3 \vee \bar{x}_1 \bar{x}_2 \bar{x}_3$	4		Non-Disjoint Bi-Decomposition
10	$(x_1 \vee x_2 \vee x_3)(\bar{x}_1 \vee \bar{x}_2 \vee \bar{x}_3)$	4		
11	$\bar{x}_1 x_3 \vee x_1 x_2$	24		
12	$x_1 \bar{x}_2 \bar{x}_3 \vee x_2 x_3$	24		
13	$(x_1 \vee \bar{x}_2 \vee \bar{x}_3)(x_2 \vee x_3)$	24		No Bi-Decomposition
14	$x_1 x_2 \vee x_2 x_3 \vee x_3 x_1$	8		
15	$x_1 x_2 \vee x_2 x_3 \vee x_1 x_3 \vee \bar{x}_1 \bar{x}_2 \bar{x}_3$	8		
16	$\bar{x}_1 x_2 x_3 \vee x_1 \bar{x}_2 x_3 \vee x_1 x_2 \bar{x}_3$	8		

$N$ : Number of the functions in the class.

Table 6.2: Number of functions.

			$n = 2$	$n = 3$	$n = 4$
All the functions			16	256	65536
Nondegenerate functions			10	218	64594
Functions with bi-decomposition	Disjoint	AND	4	44	1660
		OR	4	44	1660
		EXOR	2	26	914
	Non-disjoint		0	80	3860
	Total		10	194	8094

### 6.2 The number of functions with bi-decompositions

**Lemma 6.3** [4]: Let  $\alpha(n)$  be the number of nondegenerate functions on  $n$  variables. Then,

$$\alpha(n) = \sum_{k=0}^n \binom{n}{k} (-1)^{n-k} 2^{2^k} \sim 2^{2^n},$$

where  $a(n) \sim b(n)$  means  $\lim_{n \rightarrow \infty} \frac{a(n)}{b(n)} = 1$ .

**Lemma 6.4** A nondegenerate function  $f$  has at most one type of disjoint bi-decomposition:

1.  $f(X_1, X_2) = g_1(X_1) \cdot g_2(X_2)$ ,
2.  $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$ , or
3.  $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$ ,

where  $g_1$  and  $g_2$  are nondegenerate functions on one or more variables.

**Theorem 6.1** The number of functions  $N_{\text{disjoint}}(n)$  with disjoint bi-decompositions is  $N_{\text{disjoint}}(n) = A_{\text{dis}}(n) + O_{\text{dis}}(n) + E_{\text{dis}}(n)$ , where

$$A_{\text{dis}}(n) = n! \sum_{\substack{k_1, k_2, \dots, k_n \geq 0 \\ 1k_1 + 2k_2 + \dots + nk_n = n}} \prod_{i=1}^n \left( \frac{\alpha(i) - A_{\text{dis}}(i)}{i!} \right)^{k_i} \frac{1}{k_i!}$$

Table 7.1: Number of functions with bi-decompositions.

Decomposition Type		Number of Functions
Disjoint	AND	853
	OR	264
	EXOR	73
Non-disjoint	AND	162
	OR	91
	EXOR	42

$$O_{dis}(n)=n! \sum_{\substack{k_1, k_2, \dots, k_n \geq 0 \\ 1k_1 + 2k_2 + \dots + nk_n = n}} \prod_{i=1}^n \left( \frac{\alpha(i) - O_{dis}(i)}{i!} \right)^{k_i} \frac{1}{k_i!}$$

$$E_{dis}(n)=2n! \sum_{\substack{k_1, k_2, \dots, k_n \geq 0 \\ 1k_1 + 2k_2 + \dots + nk_n = n}} \prod_{i=1}^n \left( \frac{\alpha(i) - E_{dis}(i)}{i!} \right)^{k_i} \frac{1}{2^{k_i} k_i!}$$

where the sums are over all partitions of  $n$  except the trivial partition  $n = 0 \cdot 1 + 0 \cdot 2 + \dots + 0 \cdot (n-1) + 1 \cdot n$  (i.e. the sum is over all partitions where  $k_n = 0$ ), and where  $A_{dis}(1) = O_{dis}(1) = E_{dis}(1) = 0$ .

Table 6.2 shows the number of functions with disjoint bi-decompositions up to  $n = 4$ .

## VII Experimental Results

We analyzed the bi-decomposability of 136 benchmark functions. Over these multiple-output functions, the total number of outputs (functions) is 1908. For each function, we determined whether there exists a disjoint bi-decomposition. If none existed, we determined if there exists a non-disjoint bi-decomposition (with a single common variable). Table 7.1 summarizes our results. It is interesting that 1190 out of 1908 functions, or 62 percent, have disjoint bi-decompositions. Of the remaining 718 functions, 295 have non-disjoint decompositions. It should be noted that more than 295 functions have non-disjoint decompositions, since a function with a disjoint bi-decomposition may also have a non-disjoint bi-decomposition.

## VIII Conclusions and Comments

In this paper, we presented the bi-decomposition, a special case of functional decomposition. Disjoint bi-decompositions have the following features:

- 1) They are easy to detect; we use ISOPs or PPRMs rather than decomposition charts.
- 2) Programmable logic devices exist that realize bi-decompositions.
- 3) If the function has an OR (AND) type bi-decomposition, then we can optimize the expression separately.

We enumerated functions with bi-decompositions. Among 218 nondegenerate functions of 4 variables, 194 have bi-

decompositions. Also, we derived formulae for the number of disjoint bi-decompositions.

Since the fraction of functions with decompositions approaches to zero as  $n$  increase [4], the fraction of functions with bi-decompositions also approaches to zero as  $n$  increases. However, for 1908 functions we analyzed about 78% of them had either disjoint or non-disjoint bi-decompositions.

## References

- [1] R. L. Ashenhurst, "The decomposition of switching functions," *In Proceedings of an International Symposium on the Theory of Switching*, pp. 74-116, April 1957.
- [2] J. T. Butler, "On the number of functions realized by cascades and disjunctive networks," *IEEE Trans. Comput.*, Vol. C-24, pp. 681-690, July 1975.
- [3] H. A. Curtis, *A New Approach to the Design of Switching Circuits*, Princeton, N.J.: Van Nostrand, 1962.
- [4] M. A. Harrison, *Introduction to Switching and Automata Theory*, McGraw-Hill, 1965.
- [5] U. Keschull, E. Schubert and W. Rosenstiel, "Multilevel logic synthesis based on functional decision diagrams," *EDAC 92*, 1992, pp. 43-47.
- [6] Y.-T. Lai, M. Pedram, S. B. K. Vrudhula, "EVBDD-based algorithm for integer linear programming, spectral transformation, and functional decomposition," *IEEE Trans. CAD*, Vol. 13, No. 8, Aug. 1994, pp. 959-975.
- [7] A. A. Malik, D. Harrison, and R. K. Brayton, "Three-level decomposition with application to PLDs," *ICCD-1991*, pp. 628-633, Oct. 1991.
- [8] Y. Matsunaga, "An attempt to factor logic functions using exclusive-or decomposition," *SASIMI'96*, pp. 78-83.
- [9] S. Muroga, *Logic Design and Switching Theory*, John Wiley & Sons, 1979.
- [10] T. Sasao and K. Kinoshita, "On the number of fanout-free functions and unate cascade functions," *IEEE Trans. on Comput.*, Vol. C-28, No. 1, pp. 866-72, Jan. 1979.
- [11] T. Sasao, "Input variable assignment and output phase optimization of PLA's," *IEEE Trans. Comput.*, Vol. C-33, No. 10, pp. 879-894, Oct. 1984.
- [12] T. Sasao, "Application of multiple-valued logic to a serial decomposition of PLA's," *International Symposium on Multiple-Valued Logic*, Guangzhou, China, pp. 264-271, May 1989.
- [13] T. Sasao (ed.), *Logic Synthesis and Optimization*, Kluwer Academic Publishers, 1993.
- [14] T. Sasao, "A design method for AND-OR-EXOR three-level networks," *ACM/IEEE International Workshop on Logic Synthesis*, Tahoe City, California, May 23-26, 1995, pp.8:11- 8:20.
- [15] T. Sasao and M. Fujita (ed.), *Representations of Discrete Functions*, Kluwer Academic Publishers, 1996.
- [16] T. Sasao and J. T. Butler, "Comparison of the worst and best sum-of-products expressions for multiple-valued functions," (preprint).
- [17] M. Sauerhoff, I. Wegener, and R. Werchner, "Optimal ordered binary decision diagrams for tree-like circuits," *SASIMI'96* (to be published).
- [18] S. Yang, "Logic synthesis and optimization benchmark user guide, version 3.0," *MCNC*, Jan. 1991.